

7.4., 14.9. ← příklady (v F1)

elektrostatika d. proudy a magnetismus
 střídavý proud

skripta 1991 Bakule a spol. Příklady z el. a mag.

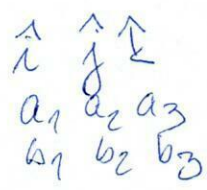
VEKTOROVÁ ANALÝZA

$|\vec{a}| = a$

$\vec{a} \cdot \vec{b} = a_1 b_1 + \dots = ab \cos \alpha = \vec{b} \cdot \vec{a}$

$\vec{a} (\vec{b} \cdot \vec{c}) = (\vec{a} \cdot \vec{b}) \vec{c}$

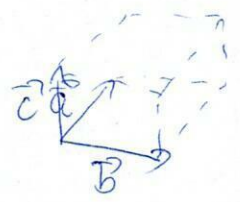
$\vec{c} = \vec{a} \times \vec{b} = \vec{n} \cdot ab \sin \alpha$
 $c_x = a_2 b_3 - a_3 b_2$
 $c_y = a_3 b_1 - a_1 b_3$
 $c_z = a_1 b_2 - a_2 b_1$



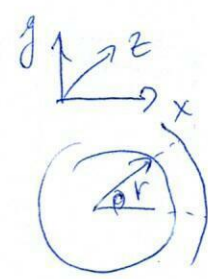
$\vec{a} \times \vec{b} = -\vec{b} \times \vec{a}$

smíšený součin $\vec{c} \cdot (\vec{a} \times \vec{b})$
 $dV_i = \frac{1}{6} \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} d\tau_i$

dejm



lamioy koef.
 $dV_i = r^2 \sin \theta dr d\theta d\phi$
 $dV_i = dx dy dz$



$dl_r = dr$
 $dl_\phi = r d\phi$

v sf. $dV = r^2 \sin \theta dr d\theta d\phi$
 v kar. $dV = dx dy dz$

$\frac{x}{r} = \sin \theta$
 $dx = r \sin \theta d\phi$

$\vec{\nabla} = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right)$

gradients

$\text{grad } f = \vec{F} = \nabla f = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right)$

divergence

$\text{div } \vec{F} = g = \nabla \cdot \vec{F} = \frac{\partial F_x}{\partial x} + \frac{\partial F_y}{\partial y} + \frac{\partial F_z}{\partial z}$

rotace (kurvesy)

$\text{rot } \vec{F} = \vec{G} = \nabla \times \vec{F} = \left(\frac{\partial F_z}{\partial y} - \frac{\partial F_y}{\partial z}, \frac{\partial F_x}{\partial z} - \frac{\partial F_z}{\partial x}, \frac{\partial F_y}{\partial x} - \frac{\partial F_x}{\partial y} \right)$

Laplaciov op.

$\Delta = \nabla \cdot \nabla = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}$

$\vec{F} = (2y, -2x, 0)$

$\boxed{\text{rot grad } f = 0} = \nabla \times \nabla f$

$\text{rot } \vec{F} = 0 \Rightarrow \vec{F} = \text{grad } f$

$\boxed{\text{div rot } \vec{G} = 0}$

$\text{div } \vec{G} = 0 \Rightarrow \vec{G} = \text{rot } \vec{G}$
 pole je potenciálov pole
 solenoidní pole

Stokesova v. $\oint \vec{F} \cdot d\vec{l} = \int \text{rot } \vec{F} \cdot d\vec{S}$

Gaussova v. $\oint \vec{F} \cdot d\vec{S} = \int \text{div } \vec{F} dV$

Pr. Učítajte divergenci a rotaci nekotoroj'ch poli. Je-li rot $\vec{F} = 0$,
 najditte sk. pole takove, aby $\vec{F} = \text{grad } f$

$\vec{F} = (2y, 2x+3z, 3y)$

$\text{div } \vec{F} = \nabla \cdot \vec{F} = \left(\frac{\partial 2y}{\partial x} + \frac{\partial (2x+3z)}{\partial y} + \frac{\partial 3y}{\partial z} \right)$
 $= 0 + 0 + 0 = 0$

$\text{rot } \vec{F} = \nabla \times \vec{F} = \begin{pmatrix} \frac{\partial 3y}{\partial y} - \frac{\partial (2x+3z)}{\partial z} & \frac{\partial 2y}{\partial z} - \frac{\partial 3y}{\partial x} & \frac{\partial (2x+3z)}{\partial x} - \frac{\partial 2y}{\partial y} \end{pmatrix}$
 $\begin{pmatrix} 3 & 0 & 2-3 \end{pmatrix} = (0, 0, 0)$

$\vec{F} = \text{grad } f = \nabla f = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z} \right)$

$3y = \frac{\partial f}{\partial z}$

$\int 3y dz = \int df$

$3yz = f_z$

$2y = \frac{\partial f}{\partial x}$

$\int 2y dx = \int df$

$2yx = f_x$

$2x+3z = \frac{\partial f}{\partial y}$

$(2x+3z)y = \int df$

$\int (2x+3z)y dy = \int df$

$(2x+3z)y^2 = f_y$

~~$f = 3yz + 2yx +$~~

$f = 2xy + 2xy + 3yz + 3yz$

$= 4xy + 6yz$

$= 2xy + 3yz$

Učítajte gradient pole.

$\vec{r} = (x, y, z)$ $r = \sqrt{x^2 + y^2 + z^2}$

$\text{grad } r = \left(\frac{\partial r}{\partial x}, \frac{\partial r}{\partial y}, \frac{\partial r}{\partial z} \right) = \left(\frac{1 \cdot 2x}{2\sqrt{x^2+y^2+z^2}}, \frac{y}{\sqrt{x^2+y^2+z^2}}, \frac{z}{\sqrt{x^2+y^2+z^2}} \right)$

$\text{grad } r^2 = \left(\frac{\partial r^2}{\partial x}, \frac{\partial r^2}{\partial y}, \frac{\partial r^2}{\partial z} \right) = (2x+2x, 2y, 2z) = 2\vec{r}$

$\text{grad } \frac{1}{r} = \left(\frac{\partial \frac{1}{r}}{\partial x}, \dots \right) = -\frac{1}{r^3} \cdot \vec{r}$
 $\frac{\partial \frac{1}{\sqrt{x^2+y^2+z^2}}}{\partial x} = -\frac{1}{2} (x^2+y^2+z^2)^{-\frac{3}{2}} \cdot 2x = -(x^2+y^2+z^2)^{-\frac{3}{2}} \cdot x$

$\text{grad } \frac{1}{r^3} = -\frac{3\vec{r}}{r^5}$
 $\frac{\partial \frac{1}{r^3}}{\partial x} = \frac{\partial (x^2+y^2+z^2)^{-\frac{3}{2}}}{\partial x} = -\frac{3}{2} (x^2+y^2+z^2)^{-\frac{5}{2}} \cdot 2x = -3x \cdot r^{-\frac{5}{2}}$

Green-Gauss $\oint f d\vec{s} = \int \nabla f dV$

$\vec{r} = (x, y, z)$ $r = (x^2 + y^2 + z^2)^{\frac{1}{2}}$ $\vec{c} = (c_1, c_2, c_3)$

$\nabla(\vec{c} \cdot \vec{r}) = \nabla(c_1 x + c_2 y + c_3 z) = (c_1, c_2, c_3) = \vec{c}$

$\nabla\left(\frac{\vec{c} \cdot \vec{r}}{r}\right)_x = \frac{1}{r} \cdot \nabla(\vec{c} \cdot \vec{r}) + \nabla\left(\frac{1}{r}\right) \cdot (\vec{c} \cdot \vec{r}) = \frac{c}{r} - \frac{\vec{r}}{r^3} (\vec{c} \cdot \vec{r}) = \frac{r^2 c - (\vec{c} \cdot \vec{r}) \vec{r}}{r^3}$

Pr. 4.

$\text{div } \vec{r} = \left(\frac{\partial x}{\partial x}, \frac{\partial y}{\partial y}, \frac{\partial z}{\partial z}\right) = (1+1+1) = 3$

$\text{rot } \vec{r} = \begin{pmatrix} \frac{\partial x}{\partial y} \\ \frac{\partial y}{\partial z} \\ \frac{\partial z}{\partial x} \end{pmatrix} \times \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} \frac{\partial z}{\partial y} - \frac{\partial y}{\partial z} \\ \dots \\ \dots \end{pmatrix} = \vec{0}$

$\text{div } \frac{\vec{r}}{r} = \nabla \cdot \frac{\vec{r}}{r} = \left(\frac{\partial}{\partial x} \frac{x}{(x^2+y^2+z^2)^{\frac{1}{2}}} + \frac{\partial}{\partial y} \frac{y}{(x^2+y^2+z^2)^{\frac{1}{2}}} + \frac{\partial}{\partial z} \frac{z}{(x^2+y^2+z^2)^{\frac{1}{2}}} \right)$

$= -r^{-3}(r^2 - x^2 + r^2 - y^2 + r^2 - z^2) = 3r^{-1} - r^{-3}(x^2+y^2+z^2) = 3r^{-1} - r^{-3} \cdot r^2 = 3r^{-1} - r^{-1} = 2r^{-1}$

$\frac{\partial}{\partial x} \frac{x}{(x^2+y^2+z^2)^{\frac{1}{2}}} = 1 \cdot (x^2+y^2+z^2)^{-\frac{1}{2}} - x \cdot \frac{1}{2} (x^2+y^2+z^2)^{-\frac{3}{2}} \cdot 2x = (x^2+y^2+z^2)^{-\frac{1}{2}} - x^2 (x^2+y^2+z^2)^{-\frac{3}{2}}$

$\text{rot } \frac{\vec{r}}{r} = \nabla \times \frac{\vec{r}}{r} = \frac{1}{r} (\nabla \times \vec{r}) + (\nabla \cdot \frac{1}{r}) \times \vec{r} = \frac{1}{r} \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} + \frac{1}{r^3} \times \vec{r} = \vec{0}$

$\text{div } \frac{\vec{r}}{r^3} = \nabla \cdot \frac{\vec{r}}{r^3} = \frac{1}{r^3} (\nabla \cdot \vec{r}) + (\nabla \cdot \frac{1}{r^3}) \cdot \vec{r} = \frac{1}{r^3} \cdot 3 + \frac{3r^2}{r^5} \cdot \vec{r} = \frac{3}{r^3} - \frac{3r^2}{r^5} = \frac{3}{r^3} - \frac{3}{r^3} = 0$

$\text{rot } \frac{\vec{r}}{r^3} = \nabla \times \frac{\vec{r}}{r^3} = (\nabla \cdot \frac{1}{r^3}) \times \vec{r} + (\nabla \times \vec{r}) \cdot \frac{1}{r^3} = -\frac{3r^2}{r^5} \times \vec{r} + 0 \cdot \frac{1}{r^3} = \vec{0}$

ELEKTROSTATIKA

Pr. 1. 2 stejne castice nahoji e $m = ?$, aly $\vec{F}_G = -\vec{F}_{el}$.

$\frac{1}{4\pi\epsilon_0} \frac{q_1 q_2}{r^2} = G \frac{m^2}{r^2}$

$m = \sqrt{\frac{e^2}{4\pi\epsilon_0 G}} = 1,86 \cdot 10^{-9} \text{ kg}$

$\frac{m}{m_{el}} = 2 \cdot 10^{21}$

$\vec{F} = q \vec{E}$

$\varphi = -\nabla f$ (intenzita)

$\vec{E} = \frac{1}{4\pi\epsilon_0} \sum \frac{q_i \vec{r}_i}{r^3}$

$E = -\nabla \varphi$ (potencial)

1 nahoj: $E = \frac{1}{4\pi\epsilon_0} \frac{q \vec{r}}{r^3}$

$\varphi = \frac{q}{4\pi\epsilon_0} \frac{1}{r}$

Pr. 1.19. $\frac{Q_1}{a_1} = N$

$\varphi = \frac{1}{4\pi\epsilon_0} \left(\frac{Q_1}{\sqrt{x^2+y^2+z^2}} - \frac{m Q_1}{\sqrt{(x-d)^2+y^2+z^2}} \right) = 0$

$\frac{Q_1}{\sqrt{x^2+y^2+z^2}} = \frac{m Q_1}{\sqrt{(x-d)^2+y^2+z^2}}$

$$\sqrt{(x-d)^2 + y^2 + z^2} = n \sqrt{x^2 + y^2 + z^2}$$

$$(x-d)^2 + y^2 + z^2 = n^2 (x^2 + y^2 + z^2)$$

$$x^2 - 2xd + d^2 + y^2 + z^2 = n^2 x^2 + n^2 y^2 + n^2 z^2$$

$$x^2(n^2-1) + 2xd + d^2 + y^2(n^2-1) + z^2(n^2-1) = 0$$

$$x^2(n^2-1) + y^2(n^2-1) + z^2(n^2-1) = -2xd + d^2$$

$$x^2 + y^2 + z^2 = \frac{d^2 - 2xd}{n^2 - 1}$$

$$\left(x + \frac{2xd}{n^2-1}\right)^2 + \frac{2xd}{n^2-1} - \frac{4d^2}{(n^2-1)^2} + y^2 + z^2 = \frac{d^2 - 2xd}{n^2-1}$$

$$\left(\frac{2xd}{n^2-1} + \frac{2xd}{n^2-1}\right)^2 + y^2 + z^2 = \frac{4d^2}{(n^2-1)^2} + \frac{d^2 - 2xd}{n^2-1} + \frac{2xd}{n^2-1}$$

$$= \frac{4d^2 + d^2 + 4d^2}{(n^2-1)^2} = \frac{d^2(d^2 + 4)}{(n^2-1)^2}$$

$$\varphi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \cdot \frac{Q}{|\vec{r} - \vec{r}'|}$$

$$E(\vec{r}) = \frac{1}{4\pi\epsilon_0} \frac{Q(\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3}$$

$$\sqrt{1+x} = 1 + \frac{x}{2} \quad |x| \ll 1$$

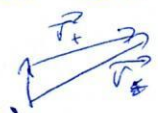
$$\frac{1}{1-x} = 1 + x \quad |x| \ll 1$$

$$\int_{\Omega} \nabla \cdot \vec{F} d\Omega = \int_{\partial\Omega} \vec{F} \cdot d\vec{S}$$

Gaussova veta

$\vec{p} = ql\vec{e}_y$ dipolový moment
 Vypočítaj te $\varphi(\vec{r})$ a $E(\vec{r})$
 $|\vec{r}| \gg l$

Pr. ∇
 dipol



$$\varphi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \left(\frac{q}{|\vec{r} - \vec{r}'_+|} + \frac{-q}{|\vec{r} - \vec{r}'_-|} \right) = \frac{q}{4\pi\epsilon_0} \left(\frac{|\vec{r} - \vec{r}'_-| - |\vec{r} - \vec{r}'_+|}{|\vec{r} - \vec{r}'_+| |\vec{r} - \vec{r}'_-|} \right)$$

$$\approx \frac{ql}{4\pi\epsilon_0} \frac{1}{r^2} \left(\frac{\sqrt{x^2 + (y + \frac{l}{2})^2} - \sqrt{x^2 + (y - \frac{l}{2})^2}}{\sqrt{x^2 + (y + \frac{l}{2})^2} \sqrt{x^2 + (y - \frac{l}{2})^2}} \right)$$

$$= \frac{ql}{4\pi\epsilon_0} \frac{1}{2r^2} \left(\sqrt{1 + \frac{(y + \frac{l}{2})^2}{x^2}} - \sqrt{1 + \frac{(y - \frac{l}{2})^2}{x^2}} \right)$$

$$= \frac{ql}{4\pi\epsilon_0} \frac{1}{2r^2} \left(1 + \frac{(y + \frac{l}{2})^2}{2x^2} - \left(1 + \frac{(y - \frac{l}{2})^2}{2x^2} \right) \right)$$

$$= \frac{ql}{4\pi\epsilon_0} \frac{1}{2r^2} \frac{y^2 + y\frac{l}{x} + \frac{l^2}{4x^2} - y^2 + y\frac{l}{x} - \frac{l^2}{4x^2}}{2x^2}$$

$$= \frac{ql}{4\pi\epsilon_0} \frac{1}{2r^2} \frac{2y\frac{l}{x}}{2x^2} = \frac{ql}{4\pi\epsilon_0} \frac{y}{r^3}$$

$$= \frac{ql}{4\pi\epsilon_0} \frac{y}{r^3} = \frac{ql}{4\pi\epsilon_0 r^3} \vec{e}_y \cdot \vec{r} = \frac{q\vec{e}_y \cdot \vec{r} \cdot l}{4\pi\epsilon_0 r^3} = \frac{\vec{p} \cdot \vec{r}}{4\pi\epsilon_0 r^3}$$

$$\vec{E} = -\vec{\nabla}\varphi = -\left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}\right) \cdot \frac{\vec{p} \cdot \vec{r}}{4\pi\epsilon_0 r^3} = -\left(\frac{\partial}{\partial x} \frac{\vec{p} \cdot \vec{r}}{4\pi\epsilon_0 r^3}, \frac{\partial}{\partial y} \frac{\vec{p} \cdot \vec{r}}{4\pi\epsilon_0 r^3}, \frac{\partial}{\partial z} \frac{\vec{p} \cdot \vec{r}}{4\pi\epsilon_0 r^3}\right) \quad (3)$$

$$r = \sqrt{x^2 + y^2 + z^2} \quad \vec{p} = ql\vec{e}_y$$

$$\varphi = \frac{1}{4\pi\epsilon_0} \cdot \frac{ql\vec{e}_y \cdot \vec{r}}{r^3} = \frac{qly}{4\pi\epsilon_0 \cdot (x^2 + y^2 + z^2)^{\frac{3}{2}}}$$

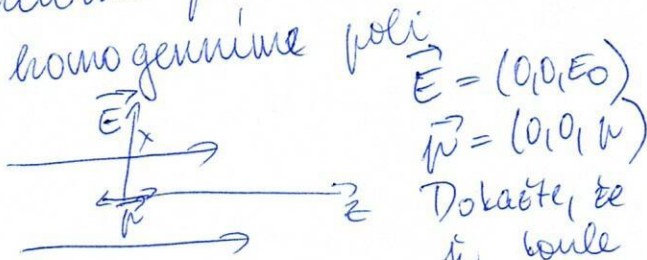
$$-\nabla\varphi_x = \left(+ \frac{qly \cdot 4\pi\epsilon_0 \cdot \frac{3}{2} (x^2 + y^2 + z^2)^{\frac{1}{2}} \cdot 2x}{(4\pi\epsilon_0 \cdot (x^2 + y^2 + z^2)^{\frac{3}{2}})^2} \right)$$

$$= \frac{qly \cdot 4\pi\epsilon_0 \cdot 3 \cdot x \cdot x}{4\pi\epsilon_0 \cdot r^5} = \frac{3qlyx}{4\pi\epsilon_0 r^5}$$

$$-\nabla\varphi_y = \frac{-3qly^2 - qlr^2}{4\pi\epsilon_0 r^5}$$

$$E = \frac{3\vec{p}z\vec{r} - \vec{p}r^2}{4\pi\epsilon_0 r^5}$$

Pr. Gradientní potenciál a intenzita dipolního a homogenního pole

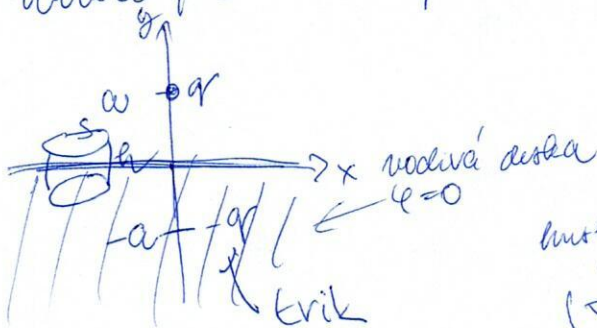


Dokažte, že ekvipotenciální plocha s 0 pot. je koule a určete její poloměr.

$$\varphi_0 = -E_0 z \quad \varphi = \frac{\vec{P} \cdot \vec{r}}{4\pi\epsilon_0 r^3} - E_0 z = \frac{Pz}{4\pi\epsilon_0 r^3} - E_0 z = 0$$

$$a = \sqrt{x^2 + z^2} = \left(\frac{P}{4\pi\epsilon_0 E_0}\right)^{\frac{1}{3}}$$

Pr. Určete pot. elstat. pole bodového náboje



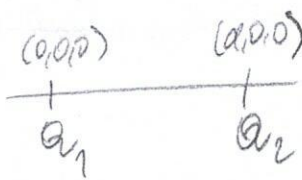
$$\varphi = ? \quad \varphi(x, y) = \frac{q}{4\pi\epsilon_0} \cdot \left(\frac{1}{\sqrt{x^2 + y^2 + a^2}} - \frac{1}{\sqrt{x^2 + y^2 + (-a)^2}} \right)$$

prázdná oblast
materiál

$$\vec{D} \cdot \vec{E} = \rho$$

$$\epsilon_0 E_y = \sigma$$

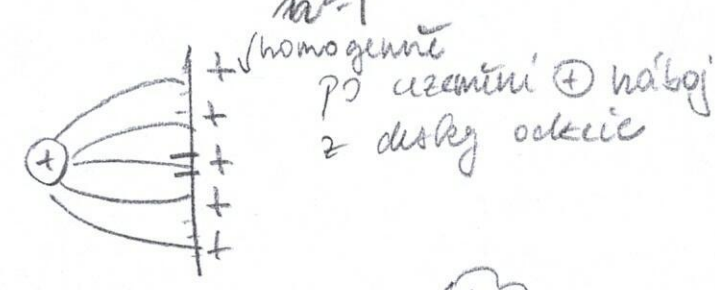
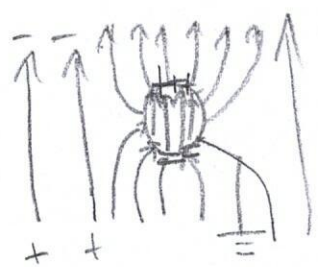
$$\int \vec{D} \cdot \vec{E} = \int \rho = \int \epsilon_0 E_y \cdot dS \quad \vec{n} \rightarrow \epsilon_0 E_y \cdot S = hS \rho = S\sigma \Rightarrow E_y = \sigma$$



$$\frac{Q_2}{Q_1} = \dots$$

$$S = \left(-\frac{d}{n^2-1}, 0, 0 \right)$$

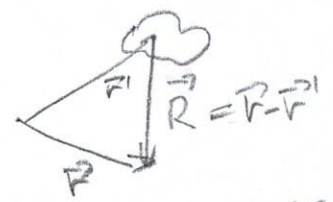
$$a = \frac{d \cdot n}{n^2-1}$$



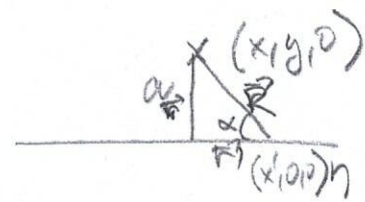
Př.
$$\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(\vec{r}')}{|\vec{r}-\vec{r}'|^3} \cdot (\vec{r}-\vec{r}') dV$$

pro bodový náboj:
$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{Q}{R^3} \cdot \vec{R}$$

$$\varphi(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int \frac{\rho(\vec{r}')}{|\vec{r}-\vec{r}'|} dV \quad E = -\nabla\varphi$$



σ dS plošná h.
 η dl lineární h.
konst.



$\frac{a}{R} = \sin \alpha \Rightarrow R = \frac{a}{\sin \alpha}$ $\frac{x'}{a} = \cot \alpha \Rightarrow \frac{dx'}{a} = -\frac{1}{\sin^2 \alpha}$
nekoničný vodič s lin. hustotou náboje η

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{\eta}{|\vec{r}-\vec{r}'|^3} (\vec{r}-\vec{r}') d\vec{r}'$$

$$E_x = \frac{1}{4\pi\epsilon_0} \int \frac{\eta}{|\vec{r}-\vec{r}'|^3} (x-x') dx' = 0$$

$$E_y = \frac{1}{4\pi\epsilon_0} \int \frac{\eta}{|\vec{r}-\vec{r}'|^3} (y) dx' = \frac{1}{4\pi\epsilon_0} \int \frac{\eta}{|\vec{r}'|^3} y dx'$$

$$= \frac{\eta}{4\pi\epsilon_0} \int \frac{\sin^2 \alpha}{a^2} \cdot a \cdot \frac{1}{-\sin^2 \alpha} dx = -\frac{\eta}{4\pi\epsilon_0} \int \frac{\sin \alpha}{a} dx$$

$$= -\frac{\eta}{4\pi\epsilon_0 a} \int \sin \alpha dx = +\frac{\eta}{4\pi\epsilon_0} [+\cos \alpha]$$

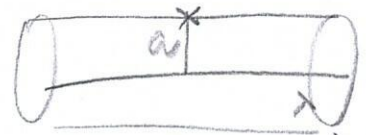
$$= \frac{+\eta}{4\pi\epsilon_0} (1+1) = \frac{+\eta}{2\pi\epsilon_0 a}$$

pomocí Gaussovy vřty:

$$\oint \vec{E} \cdot d\vec{S} = \frac{Q}{\epsilon_0} \Rightarrow \oint E ds = \frac{Q}{\epsilon_0}$$

a pro $E = \text{konst}$

$$\Rightarrow \oint E ds = E \oint ds = E S = \frac{Q}{\epsilon_0} \quad \text{pro } \vec{E} \parallel d\vec{S}$$



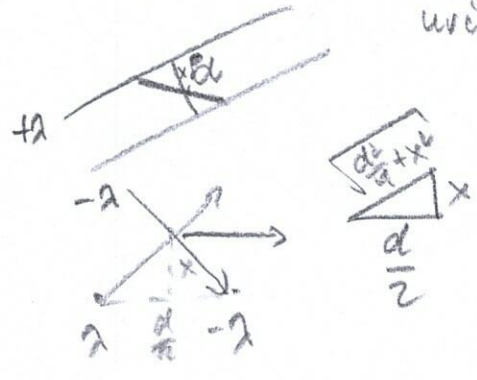
$$E = \frac{Q}{\epsilon_0 S} = \frac{Q}{\epsilon_0 2\pi a L} = \frac{\lambda \cdot L \cdot \epsilon_0}{\epsilon_0 2\pi a L} = \frac{\lambda}{2\pi \epsilon_0 a}$$

Nekupot. plocha a $\vec{E} \parallel \vec{n}$

Pr. (122)

$\lambda = \text{konst}$
určete intenzitu v bodě ve výšce x

(4)

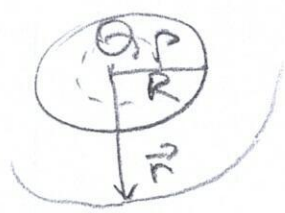


$$E = E_1 + E_2 = \frac{\lambda}{2\epsilon_0 \pi \cdot \sqrt{\frac{d^2}{4} + x^2}} \cdot \left(\frac{d/2}{x}\right) + \frac{\lambda}{2\epsilon_0 \pi \cdot \sqrt{\frac{d^2}{4} + x^2}}$$

$$= \frac{\lambda}{2\pi\epsilon_0 \left(\frac{d^2}{4} + x^2\right)} \left(\frac{d/2}{x}\right) + \frac{\lambda}{2\pi\epsilon_0 \left(\frac{d^2}{4} + x^2\right)} \cdot \left(\frac{d/2}{-x}\right)$$

$$= \frac{\lambda}{2\pi\epsilon_0 \left(\frac{d^2}{4} + x^2\right)} \left(\left(\frac{d/2}{x}\right) + \left(-\frac{d/2}{x}\right) \right) = \frac{\lambda}{2\pi\epsilon_0 \left(\frac{d^2}{4} + x^2\right)} \begin{pmatrix} d \\ 0 \end{pmatrix}$$

Pr. (119) Rovnoměrně nabitá koule



↓ dielektrická

$$\oint \vec{E} \cdot d\vec{S} = \frac{Q}{\epsilon_0}$$

opět je $\vec{r} \parallel \vec{E}$

$$Q = \frac{4}{3} \pi r^3 \rho$$

$r > R$ - vně

$$ES = \frac{Q}{\epsilon_0}$$

$$E = \frac{Q}{4\pi\epsilon_0 r^2} = \frac{\rho}{3\epsilon_0} \frac{r^3}{r^2} = \frac{\rho r}{3\epsilon_0}$$

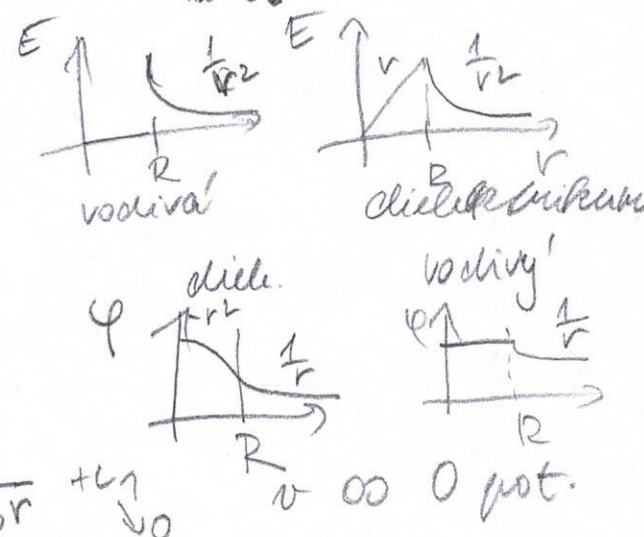
$r < R$ - uvnitř:

$$q = \frac{Q \frac{4}{3} \pi r^3 \rho}{\frac{4}{3} \pi R^3 \rho} = Q \frac{r^3}{R^3}$$

potenciál má: $r > R$

$$\vec{E} = -\nabla\varphi$$

$$\vec{E}(r) = -\frac{\partial\varphi}{\partial r}$$



$$\int \frac{+Q}{4\pi\epsilon_0 r^2} = \int + \frac{\partial\varphi}{\partial r}$$

$$\frac{+Q}{4\pi\epsilon_0} \int \frac{1}{r^2} dr = \int d\varphi$$

$$\varphi = \frac{Q}{4\pi\epsilon_0} \left(\frac{1}{r} \right) = \frac{Q}{4\pi\epsilon_0 r}$$

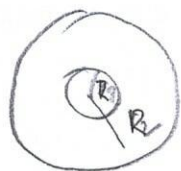
potenciál uvnitř $r < R$:

$$\vec{E}(r) = -\frac{\partial\varphi}{\partial r}$$

$$\int \frac{Qr}{4\pi R^3 \epsilon_0} = \int -\frac{\partial\varphi}{\partial r}$$

$$\varphi = -\frac{Q}{4\pi R^3 \epsilon_0} \int r dr = -\frac{Q}{4\pi R^3 \epsilon_0} \cdot \frac{r^2}{2} + C_2$$

protože potenciál je vždy spojitý!
pro $r=R$ $= \frac{-Q}{4\pi\epsilon_0 R}$



$$\varphi_1 = A_{11} Q_1 + A_{12} Q_2$$

$$\varphi_2 = A_{21} Q_1 + A_{22} Q_2$$

$$Q_1 = C_{11} \varphi_1 + C_{12} \varphi_2$$

$$Q_2 = C_{21} \varphi_1 + C_{22} \varphi_2$$

$\varphi = A Q$ A_{ij} je nějaká konst. influenční koef.

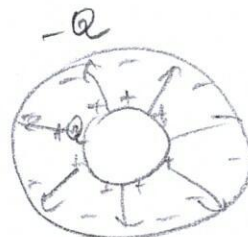
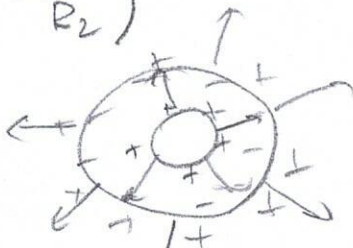
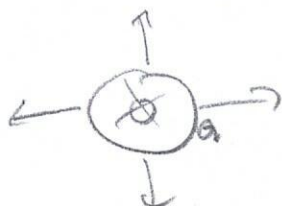
$$C_{ij} = \frac{\partial Q_i}{\partial \varphi_j}$$

$$C_{ij} = Q_i$$

$$\varphi_1 = \frac{Q}{4\pi\epsilon_0} \left(\frac{1}{R_1} - \frac{1}{R_2} \right)$$

$$\varphi_2 = \frac{Q}{4\pi\epsilon_0} \left(\frac{1}{R_2} - \frac{1}{R_2} \right)$$

$Q = Q_1 - Q_2$ kapacitní koef.



$$\left(\begin{array}{cc|cc} \frac{1}{R_1} & \frac{1}{R_2} & 1 & 0 \\ \frac{1}{R_2} & \frac{1}{R_2} & 0 & 1 \end{array} \right) \sim \left(\begin{array}{cc|cc} 1 & 0 & \frac{R_1 R_2}{R_2 - R_1} & -\frac{R_1 R_2}{R_2 - R_1} \\ 0 & 1 & -\frac{R_1 R_2}{R_2 - R_1} & \frac{R_1 R_2}{R_2 - R_1} \end{array} \right)$$

influenční k.

kapacitní k.

$C_{12} = C_{21}$
symetrie

$C_{11} = -C_{12}$
podle kondenzátoru

KAPACITA

$$C = \frac{Q}{U}$$

$$U = \varphi_2 - \varphi_1$$

Př. 1.2.6.

kondenzátor
infl. koeficientu

kapacita pomocí kap. a



$$U = \frac{Q}{4\pi\epsilon_0} \left(\frac{1}{R_1} - \frac{1}{R_2} \right)$$

$$C = \frac{Q}{U} = \frac{Q}{\frac{Q}{4\pi\epsilon_0} \left(\frac{1}{R_1} - \frac{1}{R_2} \right)} = 4\pi\epsilon_0 \frac{R_1 R_2}{R_2 - R_1}$$

$$U = \varphi_A - \varphi_B = Q \left(\frac{C_{11} - C_{12} - C_{11} + C_{21}}{C_{11} C_{22} - C_{12} C_{21}} \right)$$

Př. 1.2.7.

$$\oint \vec{E} \cdot d\vec{S} = \frac{Q}{\epsilon_0}$$



$$E = \frac{Q}{2\pi r l \epsilon_0} = \frac{\sigma \cdot 2\pi r l}{2\pi r l \epsilon_0} = \frac{\sigma R}{r \epsilon_0}$$

$$E = -\nabla \varphi$$

φ_{konst}

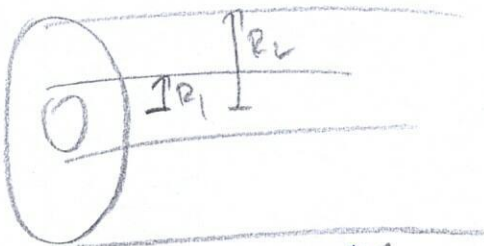
$$\int E = -\frac{\partial \varphi}{\partial r}$$

$$\int \frac{\sigma R}{r \epsilon_0} dr = -\int d\varphi$$

$$\varphi = -\frac{\sigma R}{\epsilon_0} \ln |r| + C = \frac{\sigma R}{\epsilon_0} \ln \frac{1}{r} + C$$

nemůže být 0 pot. v $\infty \rightarrow$ bude na elektrodě

$$\Rightarrow C = \frac{\sigma R}{\epsilon_0} \ln \frac{R}{R} \rightarrow \varphi = \frac{\sigma R}{\epsilon_0} \ln \left(\frac{R}{r} \right)$$



$$\phi_1 = \frac{\sigma_1 R_1}{\epsilon_0} \ln \frac{R_1}{R_1} + \frac{\sigma_2 R_2}{\epsilon_0} \ln \frac{R_1}{R_2} \quad (5)$$

$$\phi_2 = \frac{\sigma_1 R_1}{\epsilon_0} \ln \frac{R_1}{R_2} + \frac{\sigma_2 R_2}{\epsilon_0} \ln \frac{R_2}{R_2}$$

$$U = \phi_2 - \phi_1 = \frac{\sigma_1 R_1}{\epsilon_0} \ln \frac{R_2}{R_1}$$

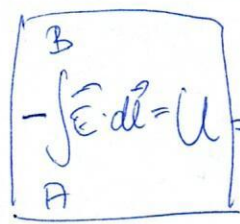
$$C = \frac{Q}{U} = \frac{2\pi \epsilon_0 l \sigma_1 R_1}{\frac{\sigma_1 R_1}{\epsilon_0} \ln \frac{R_2}{R_1}} = \frac{2\pi \epsilon_0 l}{\ln \left(\frac{R_2}{R_1} \right)}$$

$$ES = \frac{Q}{\epsilon_0} \quad E \cdot 2\pi r l = \frac{Q}{\epsilon_0}$$

$$E = \frac{Q}{2\pi \epsilon_0 l} \cdot \frac{1}{r} \Rightarrow \phi = -k \int \frac{1}{r} = -k \log \frac{1}{r} + C$$

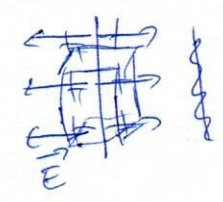
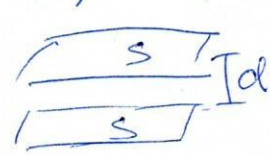
$$= k \log \frac{r_0}{r}$$

$$\phi_1 - \phi_2 = \frac{Q}{2\pi \epsilon_0 l} \left(\ln \frac{R_1}{R_1} - \ln \frac{R_1}{R_2} \right)$$



$$-\int \vec{E} \cdot d\vec{l} = U = \int_{R_2}^{R_1} \frac{Q}{2\pi \epsilon_0 l} \cdot \frac{1}{r} dr = -\frac{Q}{2\pi \epsilon_0 l} [\log R_1 - \log R_2] = \frac{Q}{2\pi \epsilon_0 l} \log \frac{R_2}{R_1}$$

Pr. (1.2.8) Kapacita deskoveho kond.



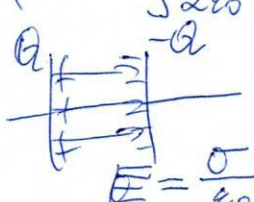
$$\oint \vec{E} \cdot d\vec{s} = \frac{Q}{\epsilon_0}$$

$$2E \cdot S = \frac{Q}{\epsilon_0} \quad C = \frac{Q}{U}$$

$$= \frac{\sigma S}{\epsilon_0} \Rightarrow E = \frac{\sigma}{2\epsilon_0}$$

$$\phi = -\int \frac{\sigma}{2\epsilon_0} dx = -\frac{\sigma}{2\epsilon_0} x$$

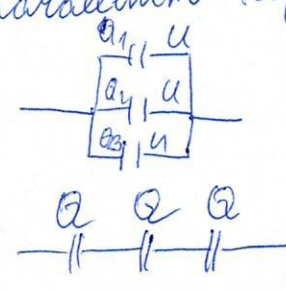
$$E = \frac{\sigma}{\epsilon_0} \quad (2 \times \frac{\sigma}{2\epsilon_0})$$



$$U = -\int \frac{\sigma}{\epsilon_0} dz = -\frac{\sigma}{\epsilon_0} (d)$$

$$C = \frac{Q}{U} = \frac{\sigma S}{\frac{\sigma d}{\epsilon_0}} = \frac{\epsilon_0 S}{d}$$

Pr. Kapacita pri serijskym a paralelnym zapojeni



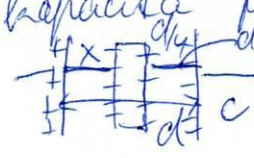
$$Q = Q_1 + Q_2 + Q_3$$

$$C = \frac{Q}{U} = \frac{Q_1 + Q_2 + Q_3}{U} = \frac{Q_1}{U} + \frac{Q_2}{U} + \frac{Q_3}{U} = C_1 + C_2 + C_3$$

$$U = U_1 + U_2 + U_3 \quad Q = Q_1 = Q_2 = Q_3$$

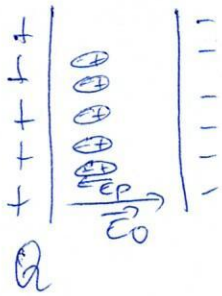
$$C = \frac{Q}{U} = \frac{Q}{\frac{Q}{C_1} + \frac{Q}{C_2} + \frac{Q}{C_3}} = \frac{Q}{\frac{1}{C} = \frac{1}{C_1} + \frac{1}{C_2} + \frac{1}{C_3}}$$

Pr. (1.2.11) deskovy kondenzator s kapacitou C. Jaka bude kapacita po vlozeni plechu?



$$\frac{1}{C} = \frac{1}{C_1} + \frac{1}{C_2} = \frac{1}{\epsilon_0} + \frac{1}{\epsilon_0} = \frac{2}{\epsilon_0} \Rightarrow C = \frac{\epsilon_0 S}{2d}$$

Př.



$$\vec{E} = \vec{E}_0 \rightarrow \vec{E}' = \vec{E}_0 + \vec{E}_p$$

$$\text{v x: } E = E_0 - E_p$$

$$E = \frac{\sigma}{\epsilon_0} - \frac{\sigma_p}{\epsilon_0}$$

$$\epsilon_0 E = \sigma - \sigma_p$$

$$\epsilon_0 E = \sigma - P$$

$$\epsilon_0 E = \sigma - \chi \epsilon_0 E$$

$$\epsilon_0 E (1 + \chi) = \sigma$$

$$\sigma_p = \vec{P} \cdot \vec{n}$$

$$P = \chi \epsilon_0 E$$

$$\rightarrow \epsilon_0 \epsilon_r E = \sigma$$

$$\epsilon_r E = \frac{\sigma}{\epsilon_0}$$

$$\vec{D} = \sigma \quad | \cdot S$$

vektorel. indukce $\oint \vec{D} \cdot d\vec{S} = Q$

Př. (1.3.1) Deskový kondenzátor o kap. C_0 , ploše S , nabitým Q .
 Přidali jsme diel. a $C_0 \rightarrow C$. Vypočítejte E, σ_p
 kond. není připojen ke zdroji $\Rightarrow Q = \text{konst}$
 $C = \frac{\epsilon_0 S}{d}$

\vec{E} před vložením diel.

$$Ed = U = \frac{Q}{C} \Rightarrow E_0 = \frac{Q}{C_0 d} = \frac{Q}{\frac{\epsilon_0 S}{d} \cdot d} = \frac{Q}{\epsilon_0 S} = \frac{\sigma S}{\epsilon_0 S} = \frac{\sigma}{\epsilon_0}$$

po vložení:

$$E = \frac{\sigma}{\epsilon_0 \epsilon_r} \Rightarrow \frac{E}{E_0} = \frac{\frac{\sigma}{\epsilon_0 \epsilon_r}}{\frac{\sigma}{\epsilon_0}} = \frac{1}{\epsilon_r}$$

σ_p :

$$-\sigma_p = \vec{P} \cdot \vec{n} = P = \chi \epsilon_0 E$$

$$= (\epsilon_r - 1) \epsilon_0 E = (\epsilon_r - 1) \epsilon_0 \frac{E_0}{\epsilon_r}$$

$$= (\epsilon_r - 1) \epsilon_0 \cdot \frac{\sigma}{\epsilon_0 \epsilon_r} = \frac{\sigma (\epsilon_r - 1)}{\epsilon_r}$$

$$\epsilon_r = \chi + 1$$

$$\chi = \epsilon_r - 1$$

U:

$$U = E \cdot d = \left(\frac{\sigma}{\epsilon_0 \epsilon_r} \right) d = \frac{E_0}{\epsilon_r} d$$

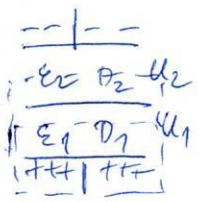
při $U = \text{konst}$:

$$\sigma = \sigma_0 \epsilon_r$$

σ_p :

$$\sigma_p = P = \chi \epsilon_0 E = (\epsilon_r - 1) \epsilon_0 \cdot E_0$$

Př. (1.3.4)



$$U = U_1 + U_2$$

$$D = D_1 = D_2$$

$$\epsilon E = \epsilon_1 E_1 = \epsilon_2 E_2$$

$$D = \frac{Q}{S} \quad D = \epsilon E$$

$$D S = Q$$

$$D = \epsilon E$$

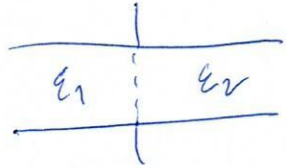
$$\epsilon_2 > \epsilon_1: E_2 < E_1$$

$$U = E_1 d + E_2 d = \frac{D}{\epsilon_1} d + \frac{D}{\epsilon_2} d = D \left(\frac{d}{\epsilon_1} + \frac{d}{\epsilon_2} \right) = \frac{Q}{S} \left(\frac{d}{\epsilon_1} + \frac{d}{\epsilon_2} \right)$$

$$\frac{1}{C} = \frac{Q U}{Q} = \frac{1}{C_1} + \frac{1}{C_2} = \frac{d}{\epsilon_1 S} + \frac{d}{\epsilon_2 S}$$

Př.

$$U_1 = U_2 = U = Ed$$



$$U = Q = Q_1 + Q_2 = D_1 \frac{S}{2} + D_2 \frac{S}{2} = \frac{\epsilon_1 E S}{2} + \frac{\epsilon_2 E S}{2}$$
$$= \frac{Ed \epsilon_1 S}{2d} + \frac{Ed \epsilon_2 S}{2d} \Rightarrow C = C_1 + C_2$$

(6)

Př. (14.1)

Energie kondenzátoru

$$W = \int_0^Q u dQ = \frac{1}{C} \int_0^Q Q dQ = \frac{1}{2C} Q^2 = \frac{1}{2} QU = \frac{1}{2} CU^2$$

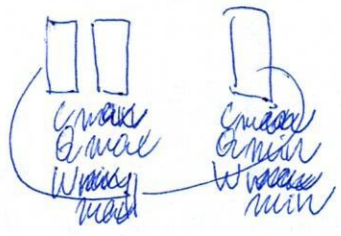
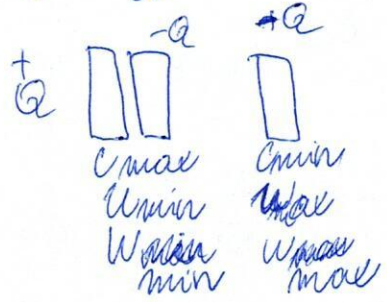
$$C = \frac{\epsilon S}{d}$$

$$C = \frac{Q}{U}$$

$$D = \epsilon E$$

$$Q = DS$$

$$F = -grad W$$



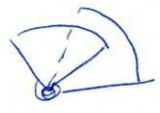
zdroj musí vykonat větší práci na dojení náboje

Př.

(14.1) osobný kondenzátor

min. kapacita C_0 při změně $C_{max} \rightarrow C_0$ je $U = konst?$

jakou W vykonáve jistěže na elektrodách



$$W_0 = \frac{1}{2} C_0 U^2$$

$$W_{max} = \frac{1}{2} C_{max} U^2$$

$$\Rightarrow \delta W = \frac{1}{2} (C_{max} - C_0) U^2$$

jakou práci vykonáme jistěže byl nabit na napětí U a při otáčení zdroj odpojíme?

$$W_0 = \frac{1}{2} \frac{Q^2}{C_0}$$

$$W_{max} = \frac{1}{2} \frac{Q^2}{C_{max}}$$

$$\delta W = \frac{1}{2} \left(\frac{Q^2}{C_0} - \frac{Q^2}{C_{max}} \right) = \frac{Q^2}{2} \left(\frac{1}{C_0} - \frac{1}{C_{max}} \right) = \frac{Q^2}{2} \frac{C_{max} - C_0}{C_0 C_{max}}$$

Př.

jaká síla působí na elektrony desky kond. nabitého na nap. U , plocha je S vzd. x .

$$C = \frac{\epsilon S}{x}$$

$$F = -grad W$$

$$\frac{1}{x}$$

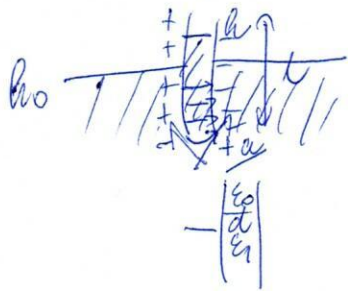
$$W = \frac{1}{2} CU^2 = \frac{1}{2} \frac{\epsilon S}{x} U^2$$

$$F_x = - \frac{\partial}{\partial x} \left(\frac{1}{2} \frac{\epsilon S}{x} U^2 \right) = + \frac{1}{2} \epsilon S U^2 \cdot \left(\frac{1}{x^2} \right) = \frac{1}{2} \frac{\epsilon S U^2}{x^2}$$

$$F_y = 0$$
$$F_z = 0$$

$$\vec{F} = \left(\frac{1}{2} \frac{\epsilon S U^2}{x^2}, 0, 0 \right)$$

Pr. (1.4.6) kond. ponořený do kapaliny
kap. vysoupa! proč?



$$mgh = \frac{1}{2} cu^2$$

$$h = \frac{1}{2} \frac{cu^2}{mg}$$

$$W = \frac{1}{2} (C_1 + C_2) u^2 = \frac{1}{2} \left(\frac{\epsilon_1 a d h}{d} + \frac{\epsilon_0 (l-h) a}{d} \right) u^2$$

$$C = \frac{\epsilon S}{d}$$

$$= \frac{a}{2d} (\epsilon_1 h - \epsilon_0 (l-h)) u^2 = \frac{l \cdot a}{2d} (l(\epsilon_1 - \epsilon_0) + \epsilon_0 h) u^2$$

$$mgh = \frac{a}{2d} (l(\epsilon_1 - \epsilon_0) + \epsilon_0 h) u^2$$

zderivujeme \rightarrow grad $\rightarrow F$
 $mgh = F$

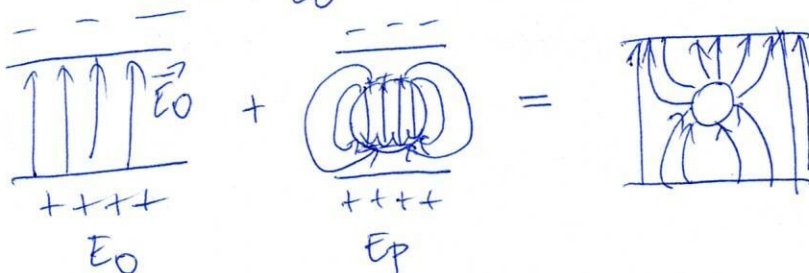
Pr. bod. náboj: $W = QU$

dipol: $W = -\vec{p} \cdot \vec{E}_0$

dielektr. těles: $W = -\int \vec{p}_0 \cdot \vec{E}_0 dV$

dielektr. kuličky: $W = -\int \vec{p}_m \cdot \vec{E}_0 dV + \frac{1}{2} \int \vec{p}_m \cdot \vec{E}_0 dV = -\frac{1}{2} \int \vec{p}_m \cdot \vec{E}_0 dV$

Pr. do homog. pole \vec{E}_0 byla vložena koule o pol. R. Spočítejte výslednou energii (jiz mickéto diele.) koule.



$$W = -\frac{1}{2} \int \vec{p}_m \cdot \vec{E}_0 dV$$

$$\vec{p} = \epsilon_0 \chi \vec{E}$$

$$\vec{E} = \vec{E}_0 + \vec{E}_p$$

$$\sigma_p = \vec{p} \cdot \vec{n} = P \cos \vartheta$$

$$E = E_0 + \frac{P}{3\epsilon_0} = E_0 - \frac{\epsilon_0 \chi E}{3\epsilon_0}$$

$$E \left(1 - \frac{\epsilon_0 \chi}{3\epsilon_0} \right) = E_0 \Rightarrow E = \frac{E_0}{1 - \frac{\epsilon_0 \chi}{3\epsilon_0}} = \frac{E_0}{\frac{3 - \chi}{3}} = \frac{3E_0}{3 - \chi}$$

$$= \frac{3E_0}{3 - (\epsilon_r - 1)}$$

$$P = \frac{(\epsilon - \epsilon_0) 3\epsilon_0 E_0}{2\epsilon_0 + \epsilon}$$

$$W = -\frac{1}{2} \frac{4}{3} \pi R^3 \cdot \frac{(\epsilon - \epsilon_0) 3\epsilon_0 E_0}{2\epsilon_0 + \epsilon} \cdot E_0 = \frac{(\epsilon_0 - \epsilon) \epsilon_0 E_0^2}{2\epsilon_0 + \epsilon}$$

$$E = \frac{1}{4\pi\epsilon_0} \int \frac{\sigma}{R^2} dS$$

$$E_p = \frac{-P}{3\epsilon_0}$$

ELEKTRICKÝ PROUD, OBVODY.

Př. Zelený drát jaká je V-A charakteristika variátoru? R závisí lineárně na teplotě.

$$R_t = R_0 (1 + \alpha t + \beta t^2 + \dots)$$

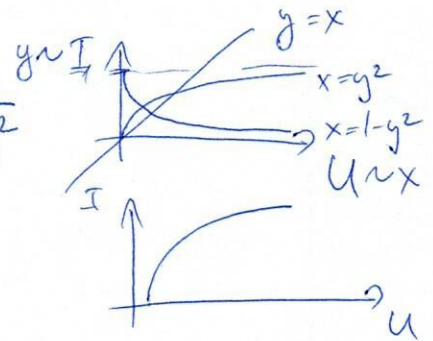
$$R = \frac{U}{I} = R_0 (1 + \alpha \Delta t) = R_0 (1 + \alpha g UI)$$

$$U (1 - R_0 I^2 \alpha g) = R_0 I$$

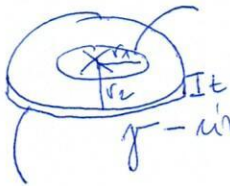
$$U = \frac{R_0 I}{1 - R_0 I^2 \alpha g}$$

$$\sqrt{R_0 \alpha g I} = y$$

$$U = \frac{R_0 I}{1 - y^2} \cdot \frac{\frac{\alpha g}{R_0}}{\frac{\alpha g}{R_0}} = \sqrt{\frac{\alpha g}{R_0}} U = x = \frac{y}{1 + y^2}$$



Př. deska stanovte odpor mezi vodiči.



$$R = \frac{U}{I}$$

$$E = \frac{\sigma}{\epsilon_0} \cdot \frac{r_1}{r} \quad \text{-- už víme}$$

$$U = \frac{\sigma r_2}{\epsilon_0} \ln \frac{r_2}{r_1} - \frac{\sigma r_1}{\epsilon_0} \ln \frac{r_1}{r_1} = \frac{\sigma r_2}{\epsilon_0} \ln \frac{r_2}{r_1}$$

$$I = \int \vec{i} \cdot d\vec{S} = \gamma \int E dS = \gamma \frac{\sigma r_1}{\epsilon_0} \frac{r_1}{r} 2\pi r l = \dots$$

$$\vec{i} = \gamma \vec{E}$$

$$\frac{I dS}{I} = \frac{\gamma r_1}{R} \frac{E r_1}{U}$$

$$R = \frac{U}{I} = \frac{\frac{\sigma r_2}{\epsilon_0} \ln \frac{r_2}{r_1}}{\gamma \frac{\sigma r_1}{\epsilon_0} \frac{r_1}{r} 2\pi l} = \frac{\ln \frac{r_2}{r_1}}{\gamma 2\pi l}$$

jinak: $dR = \frac{dR}{\gamma S(r)} \Rightarrow R = \frac{1}{\gamma} \int_{r_1}^{r_2} \frac{dr}{2\pi r l} = \frac{1}{\gamma 2\pi l} \int_{r_1}^{r_2} \frac{dr}{r}$

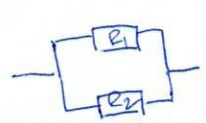


řířiové odpory

$$U = U_1 + U_2$$

$$I = I_1 = I_2$$

$$R = \frac{U}{I} = \frac{U_1 + U_2}{I} = R_1 + R_2$$



řířiové odpory

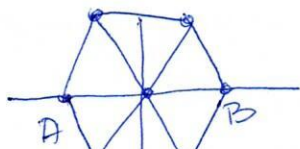
$$U = U_1 = U_2$$

$$I = I_1 + I_2$$

$$R = \frac{U}{I} = \frac{U}{I_1 + I_2}$$

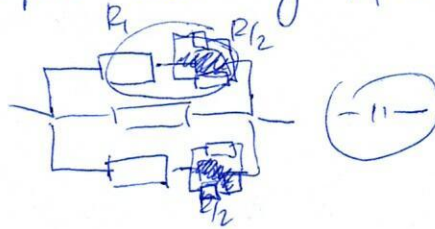
$$R^{-1} = \frac{I_1 + I_2}{U} = \frac{I_1}{U} + \frac{I_2}{U} = R_1^{-1} + R_2^{-1}$$

Pr. 5.14.



Určete odpor mezi body A, B.

$\varphi = \text{konst.}, \vec{I} = \vec{0}$



$$R_1 = \frac{4R}{3} = \frac{3}{2}R + R$$

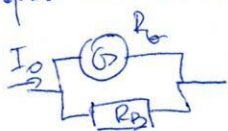
$$\frac{1}{\frac{R_1}{2}} + \frac{1}{R} = \frac{3}{R}$$

$$\frac{2}{R_V} = \frac{6}{4R} + \frac{1}{R} = \frac{5}{2}R$$

$$\frac{1}{2}R_V = \frac{5}{2}R \quad R_V = \frac{5}{2}R$$

Pr. 5.11.

Ke galvanometru s vnitřním odporem R_G je přip. boční s odp. R_B , který 10x sníží citlivost Galvanometru. Jaký odpor obvod musíme připojit, aby to fungovalo? abychom citlivost snížili 10x?



$$I_G = \frac{1}{10} I_0 \quad U = R_G I_0 = R_B I_1$$

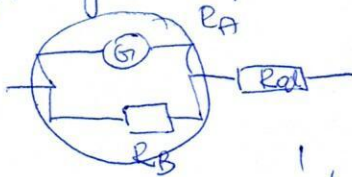
$$I_0 = I_B + I_G \Rightarrow I_B = \frac{9}{10} I_0$$

$$R_B = \frac{U_B}{I_B} = \frac{U_G}{\frac{9}{10} I_0} = \frac{10}{9} R_G \quad (\leftarrow \text{práda})$$

$$I_B = 9 I_G \quad R = \frac{U}{I}$$

$$\frac{U_B}{R_B} = 9 \frac{U_G}{R_G} \Rightarrow R_B = \frac{1}{9} R_G$$

Připojíme ještě odpor tak, aby R bylo stejné jako R_G .



$$\frac{1}{R_G} + \frac{1}{R_B} = \frac{1}{R_A}$$

$$\frac{1}{R_G} + \frac{9}{R_G} = \frac{1}{R_A} \Leftrightarrow \frac{1}{R_G} + \frac{1}{\frac{1}{9}R_G} = \frac{1}{R_A}$$

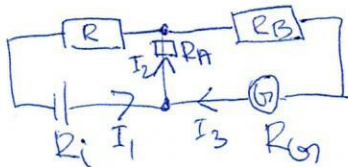
$$\frac{10}{R_G} = \frac{1}{R_A} \Rightarrow R_A = \frac{1}{10} R_G$$

$$R_{od} + \frac{1}{10} R_G = R_G$$

$$R_{od} = \frac{9}{10} R_G$$

Kirchoffovy zákony

Pr. 5.11b



g uzlů, poč. nezávislých je $g-1$

$$\sum I_i = 0$$

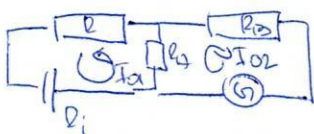
$$I_1 + I_3 = I_2$$

n větví, l smyček, poč. nezávislých je $n-(g-1)$

$$\sum R_i I_i = \sum \epsilon_i \quad \text{I}_1(R+R_i) + I_2 R_A = \epsilon$$

$$I_{01}(R+R_i+R_A) + I_{02} R_A = \epsilon$$

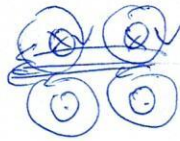
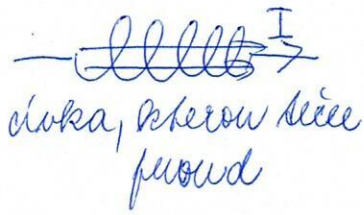
$$I_{02}(R_A+R_B+R_G) + I_{01} R_A = 0$$



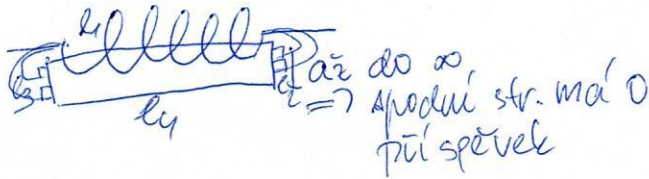
Pr. Užitím amperova z. $\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{celk}}$

(8)

3.1.6. učebe vrtah meri inderisou a mag. polem wlenoidu.



$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{celk}} = \int_{C_1} B dl + \int_{C_2} B dl + \int_{C_3} B dl$$



$$+ \int_{C_4} \vec{B} \cdot d\vec{l} = \int_{C_1} B dl$$

$C_4 \rightarrow \infty \rightarrow \vec{B} = \vec{0}$

$$\Rightarrow B l_1 = \mu_0 N I$$

$$= \mu_0 n l_1 I$$

$$B = \mu_0 n I$$

$$n = \frac{N}{l_1} \text{ hustota smyček}$$

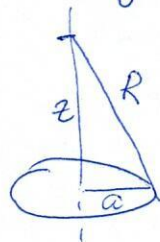
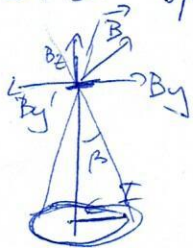
vekt. potenciál

$$\vec{A} = \frac{\mu_0 I}{4\pi r} \int \frac{d\vec{l}}{R}$$

$$\vec{B} = \text{rot } \vec{A}$$

(obdobně jako $\varphi = \frac{1}{4\pi\epsilon_0} \int \frac{Q}{R}$ $\vec{E} = -\text{grad } \varphi$)

Pr. 3.1.13. Gpčítejte mag. pole na ose zřivisku



$$R^2 = z^2 + a^2$$

$$\vec{B} = \frac{\mu_0 I}{4\pi r} \int \frac{d\vec{l} \times \vec{R}}{R^3}$$

my máme jen B ve směru osy z

$$\vec{B} = \frac{\mu_0 I}{4\pi r} \int \frac{dl \cdot R \cdot \sin \alpha}{R^3}$$

$$= \frac{\mu_0 I}{4\pi} \cdot \frac{1}{R^2} \cdot \sin \alpha \cdot \int dl = \frac{\mu_0 I}{4\pi} \cdot \frac{1}{R^2} \cdot 2\pi a \cdot 1 = \frac{\mu_0 I}{2R^2} \cdot a$$

$$\sin \alpha = 1$$

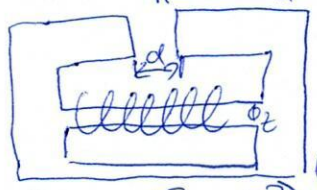
$$\alpha = 90^\circ$$



$$B_z = B \cos \beta = B \cdot \frac{a}{R} = \frac{\mu_0 I a^2}{2R^3}$$

MAGNETICKÉ OBVODY

R. 3.2.2.



Najdite intenzitu mag. pole
& merenie.

edvoj magnetomotivického napetia
poč. zdruho jako

$$\oint \vec{B} \cdot d\vec{l} = \mu I \quad \left| \quad \mathcal{F} = \oint \vec{H} \cdot d\vec{l} = NI$$

$$\oint \vec{H} \cdot d\vec{l} = I \quad \left| \quad \Phi = \int \vec{B} \cdot d\vec{S}$$

mag. tok $R_m = \int \frac{dl}{\mu S}$
mag. odpor

$\vec{B} = \mu \vec{H}$ (jako $\vec{D} = \epsilon \vec{E}$)

$U = \int \vec{E} \cdot d\vec{l}$ | $U = RI$
 $U_m = \int \vec{H} \cdot d\vec{l}$ | $U_m = R\Phi$

$\Sigma = RI$

$\mathcal{F} = R_m \Phi = NI$

\vec{B} se při $\vec{S} = \text{konst}$ nemění,
mění se \vec{H}
plaví křiv

$\Phi_2 R + \Phi_H R$

$\Phi_2 = \Phi_H + \Phi_1$
 $\Phi_1 R + \Phi_2 R = \mathcal{F}$
 $\Phi_2 R + (20R + R) \Phi_H = \mathcal{F}$

$\Phi_2 R + \Phi_H 21R = \Phi_1 R + \Phi_2 R$
 $\Phi_H = \frac{\Phi_1 R}{21R} = \frac{\Phi_1}{21}$

$\Phi_H = \frac{\mathcal{F} - \Phi_1 R}{21R} = \frac{\mathcal{F} - (\Phi_H + \Phi_1) R}{21R}$

$0 = \mathcal{F} - 21R\Phi_H - \Phi_H R - \Phi_1 R$
 $\Phi_H = \frac{\mathcal{F} - \Phi_1 R}{22R}$

$\Phi_H = \frac{\mathcal{F} - 21\Phi_H R}{22R}$

$22R\Phi_H = \mathcal{F} - 21\Phi_H R$

$43\Phi_H R = \mathcal{F}$

$\Phi_H = \frac{\mathcal{F}}{43R}$

$H_m d = 20R \left(\frac{\mathcal{F}}{43R} \right) I$

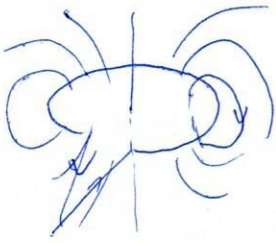
$H_m = \frac{20\mathcal{F}}{43d}$

$\int \vec{H} \cdot d\vec{l} = \int H dl = Hd$

jinak: $\Phi = \int \vec{B} \cdot d\vec{S} = \int B dS = BS = \frac{\mathcal{F}}{43R}$

$R_m = \frac{d}{\mu S}$ $\mu HS = \frac{\mathcal{F}}{43R} \Rightarrow H = \frac{\mathcal{F} \mu S}{\mu S \cdot 43 \cdot d}$

poznámka k minulému cv.



znali jsme směr, proto jsme místo

$$\vec{B} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{l} \times \vec{R}}{R^3}$$

počítali

$$B = \frac{\mu_0 I}{4\pi} \int \frac{dl \sin \alpha}{R^2}$$

mohli jsme počítat

$$B_z = \frac{\mu_0 I}{4\pi} \int \frac{dl \sin \alpha}{R^2 \sqrt{a^2 + z^2}}$$

projít na osu z

což vyjde stejně jako to, co jsme počítali minule.

Další př. se dal spočítat z $\oint H \cdot d\vec{l} = \Phi_2 \cdot 2\pi R_m$

nebo $\oint \vec{B} \cdot d\vec{s} = \Phi$

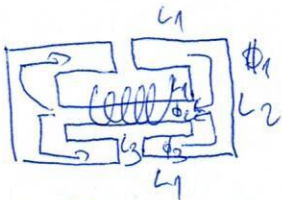
$$H = \frac{20I}{43d} \quad \vec{B} = \mu \vec{H}$$

$$\mu H S = \Phi$$

$$R_m = \frac{R_m}{\mu_0} = \frac{d}{\mu_0 S \cdot 20}$$

$$H = \frac{\Phi \mu_0 S \cdot 20}{43 d \mu_0} = \frac{20\Phi}{43d}$$

Př. 3.2.5.



kolik A musí být v závitcích, aby v mezerách bylo pole B. Známe L_1, S .

$$\oint \vec{H} \cdot d\vec{l} = NI$$

$$R_m = \int \frac{dl}{\mu S} = \frac{l}{\mu S}$$

$$\Phi_2 = \Phi_1 + \Phi_3 \quad \Phi_1 = \Phi_2$$

$$NI = \Phi_1 \left(\frac{L_1 + L_2}{\mu S} + \frac{L_3}{\mu_0 S} \right) + 2\Phi_1 \frac{L_1}{\mu S}$$

$$NI = 3\Phi_1 \frac{L_1}{\mu S} + \Phi_1 \frac{L_2}{\mu S} + \Phi_1 \frac{L_3}{\mu_0 S}$$

$$\Phi_1 = BS$$

$$NI = \Phi BS \left(3 \frac{L_1}{\mu S} + \frac{L_2}{\mu S} + \frac{L_3}{\mu_0 S} \right) \Rightarrow B = \frac{N}{S} \left(3 \frac{L_1}{\mu} + \frac{L_2}{\mu} + \frac{L_3}{\mu_0} \right)$$

Př. 3.3.3

$$\mathcal{E} = - \frac{\partial \Phi}{\partial t}$$

elektromotorické napětí

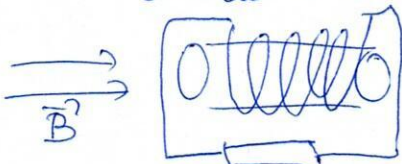
$$\Phi = \int \vec{B} \cdot d\vec{S}$$

- mění se B
- mění se S

• mění se Φ

tot $\Phi = LI$ jako $Q = CU$
induktivnost

tubka z izolačního materiálu



N závitů
 \vec{B} homog. mag. pole
známe D - průměr cívky

máme spočítat proudový impulz, ke kterému dojde při otočení o 180°

$$\Phi_1 = BS = B \cdot \pi \left(\frac{D}{2}\right)^2 N$$

$$\Phi_2 = -BS = -B \pi \left(\frac{D}{2}\right)^2 N$$

př. impulz je $\int I dt$ $\mathcal{E} = -\mathcal{E} \Delta t = \Delta \Phi$
napěťový impulz je tedy $\Phi_2 - \Phi_1 = -\pi B \frac{D^2}{2} N$

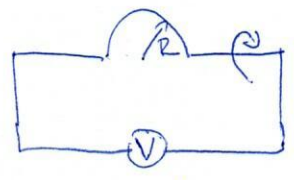
Př. 3.3.5.

první část

se otáčí v homog. mag. poli s frekvencí f .

Voltmetr ukazuje napětí U .

Jaká je mag. indukce B ?



$\omega = 2\pi f$

$$\Phi = \int \vec{B} \cdot d\vec{S} = \int B \cos \varphi \, dS = \int B \cos \omega t \, dS$$

$$= \int B \cos(2\pi f t) \, dS = B \cos(2\pi f t) S$$

$$= B \cos(2\pi f t) \frac{\pi R^2}{2}$$

$$\mathcal{E} = - \frac{\partial \Phi}{\partial t} = + \frac{B \pi R^2}{2} \cdot \sin(2\pi f t) \cdot 2\pi f = B \pi R^2 f \sin(2\pi f t)$$

Voltmetr měří časovou střední hodnotu (nestihá se měnit)

$$U_{2\pi f t}^2 = \frac{1}{T} \int_0^T u^2 dt$$

$$\int_0^T \sin^2 t + \int_0^T \cos^2 t = \int_0^T 1 dt = T$$

$$A + A = T \Rightarrow A = \frac{T}{2}$$

$$\int_0^T \sin^2 dt = A = U_{2\pi f t}^2 = \frac{T}{2}$$

$$U_{2\pi f t} = \frac{T}{\sqrt{2}}$$

$$U_{2\pi f t} = \frac{U_m}{\sqrt{2}}$$

$$U_{2\pi f t}^2 = \frac{\pi^2 R^2 B^2 f^2}{T^2} \int_0^T \sin^2(2\pi f t) dt = \frac{\pi^2 R^2 B^2 f^2}{T^2} \cdot \frac{T}{2}$$

$$= \frac{\pi^2 R^2 B^2 f^2}{2}$$

$$U_{2\pi f t} = \frac{\pi R^2 B f}{\sqrt{2}}$$

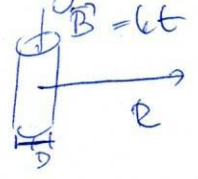
amplituda proudu (vn. odpor Voltmetru je r)

Př. 3.3.12

železný kruhový proudový

$$I_{max} = \frac{\pi^2 R^2 B f}{r}$$

elektrického



nejde intenzitu el. pole ve vzd. R

$$\int_A^B \vec{E} \cdot d\vec{e} = U_{AB}$$

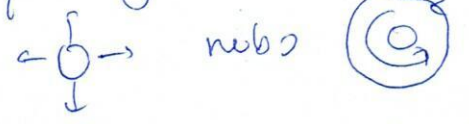
$$\oint_A^A \vec{E} \cdot d\vec{e} = 0 \quad \text{ne elast.}$$

$$\quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \text{ne mag. ne}$$

$$\oint \vec{E} \cdot d\vec{e} = - \frac{\partial \int \vec{B} \cdot d\vec{S}}{\partial t}$$

el. pole je buď

$$\int_{\text{rot}} \vec{E} \cdot d\vec{S} = - \frac{\partial \int \vec{B} \cdot d\vec{S}}{\partial t}$$



$$\text{rot } \vec{E} + \frac{\partial \vec{B}}{\partial t} = \vec{0}$$

ve směru, rozpor s Gauss.v.

$$E \cdot 2\pi R = - \frac{\partial (k t \pi \frac{R^2}{4})}{\partial t} = -k \pi \frac{R^2}{4}$$

$$E = - \frac{k R}{8}$$

$$\begin{aligned} \Phi_1 &= L_1 I_1 + M_{12} I_2 \\ \Phi_2 &= M_{21} I_1 + L_2 I_2 \end{aligned}$$

\uparrow vzájemná indukčnost \uparrow vlastní indukčnost

$$\begin{aligned} Q_1 &= C_{11} \varphi_1 + C_{12} \varphi_2 \\ Q_2 &= C_{21} \varphi_1 + C_{22} \varphi_2 \end{aligned}$$

\uparrow influenční koef. \uparrow kapacitní koef.

$\varphi = A Q$
 potenciálové koef.

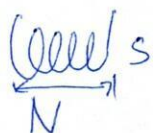
(10)

pro 1 smyčku: $\Phi = LI$

$$\mathcal{E} = - \frac{\partial \Phi}{\partial t} = -L \frac{\partial I}{\partial t}$$

$\oint \vec{E} \cdot d\vec{l} = 0$ platí i pro stacionární el. pole

Pr. 3.4.7. dlouhá válcová cívka. Chceme vyjádřit pro indukčnost.



$$\Phi = LI \Rightarrow L = \frac{\Phi}{I} = \frac{\mu N^2 S}{l I} = \frac{\mu N^2 S}{l}$$

$$\frac{\Phi}{N} = \oint \vec{B} \cdot d\vec{S} = BS \quad \mu = \frac{\mu_0 I N}{l} \cdot S$$

pro solenoid platí: $\vec{B} = \frac{\mu I N}{l}$

Pr. $\vec{A}(\vec{r}) = \frac{\mu}{4\pi} \int \frac{\vec{i}(r')}{R} dV$

pro vodič, kterým protéká proud

3.4.1. $\vec{r} = \vec{r}' - \vec{r}$

$$\vec{A}(\vec{r}) = \frac{\mu I}{4\pi} \int \frac{d\vec{l}}{R}$$

$$L = \frac{\Phi}{I} = \frac{\int \vec{B} \cdot d\vec{S}}{I} = \frac{\int \text{rot} \vec{A} \cdot d\vec{S}}{I} = \frac{\oint \vec{A} \cdot d\vec{l}}{I}$$

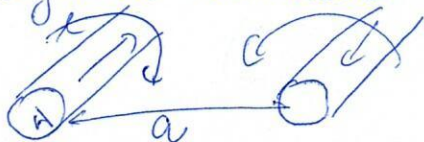
$$\vec{B} = \text{rot} \vec{A}$$

$$= \frac{\mu_0 I}{4\pi R} \oint d\vec{l} \cdot d\vec{l}$$

Pr. 3.4.3. dvě smyčky dokážte, že $M_{12} = M_{21}$

jedno $d\vec{l}$ bude u jedné cívky a druhé $d\vec{l}'$ u druhé

Pr. 3.4.11. vzájemná indukčnost dvou vodičů



1. vlastní indukčnost indukčnost

kte plochou mezi vodiči na jednotku délky

$$M = \frac{\Phi}{I} =$$

$$\Phi_L = \frac{\Phi}{I} = \int \frac{\vec{B} \cdot d\vec{S}}{e} = \int_r^{r+a} \int_{\phi=0}^{2\pi} \frac{\mu_0 I}{2\pi R} \cdot d\vec{l} \cdot d\vec{R}$$

$$= \int_r^{r+a} \frac{\mu_0 I}{2\pi R} \cdot d\vec{R} = \frac{\mu_0 I}{2\pi} \int \frac{1}{R} d\vec{R}$$

$$= \frac{\mu_0 I}{2\pi} [\log |R|]_r^{r+a}$$

$$= \frac{\mu_0 I}{2\pi} \log \frac{r+a}{r}$$

- příspěvek 1 vodiče

jsou 2 a příspěvky se sečítají $\Rightarrow \Phi = 2 \frac{\mu_0 I}{2\pi} \cdot \log \frac{r+a}{r}$

$$= \frac{\mu_0 I}{\pi} \log \frac{r+a}{r}$$

$$M = \frac{\mu_0 I}{\pi I} \log \frac{r+a}{r} = \frac{\mu_0}{\pi} \log \frac{r+a}{r}$$

$$W = \int_0^Q U I dt$$

pro kondenzátor: $W = \int_0^Q u dq = \frac{1}{C} \int_0^Q q dq = \frac{1}{2} \frac{Q^2}{C} = \frac{1}{2} QU = \frac{1}{2} Cu^2$

$$\frac{dq}{dt} = I \quad u dt = -L dI$$

$$W_m = \int u I dt = L \int_0^I I dI = \frac{1}{2} LI^2 = \frac{1}{2} I \Phi = \frac{1}{2} \frac{\Phi^2}{L}$$

analogicky $W = \frac{1}{2} \int \vec{E} \cdot \vec{D} dV \quad W_m = \frac{1}{2} \int \vec{B} \cdot \vec{H} dV$

v předchozím případě

$$W_m = \frac{1}{2} \int \frac{B^2}{\mu} dV = \frac{1}{2} \int_0^r \frac{\mu^2 I^2}{4\pi^2} \cdot \frac{R^2}{r^4} \cdot \frac{1}{\mu} \cdot 2\pi R dr = \frac{1}{2} \cdot \frac{\mu I^2}{4\pi R} \cdot \frac{2\pi R}{r^3} \int_0^r r^3 dr$$

$$= \frac{\mu I^2 R}{16\pi} \quad dV = 2\pi R r dr$$

$$W_m = \frac{\mu I^2 R}{16\pi} = \frac{1}{2} LI^2$$

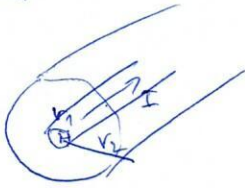
$$L_{\text{calk.}} = \frac{2\mu I^2 R}{16\pi} = \frac{\mu R}{8\pi}$$

$$L_1 = \frac{L_{\text{calk.}}}{2} = \frac{\mu}{8\pi}$$

$$L = 2 \cdot L_1 = \frac{\mu}{4\pi}$$

$$L = \frac{\mu}{4\pi} \left(1 + 4 \log \left(\frac{r+a}{r}\right)\right)$$

Pr. 4.1.11. Indukčnost na jednotku délky koaxiálního vedení



$$L = \frac{\mu_0}{4\pi} \left(\frac{1}{2} + 2 \log \left(\frac{r_2}{r_1} \right) \right)$$

proud teče jen jedním $\rightarrow \cdot \frac{1}{2}$
od r do $r+a$ \rightarrow od r_1 do r_2

Pr. 3.5.2 energie mag. pole v toroidu



$$\vec{B} =$$

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I N$$

$$B \cdot 2\pi R = \mu_0 I N$$

$$B = \frac{\mu_0 I N}{2\pi R}$$